

Estun Automation Co., Ltd.

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Full Digital AC Servo System





ALL DIGITAL AC SERVO SYSTEMS

Estun Automation Co., Ltd. is acknowledged as a leading domestic product and service provider of core components of high-end intelligent equipment, industrial robots and intelligent manufacturing systems.

As one of the most influential enterprises in the field of motion control in China, Estun's core automation component product line has completed the strategic transformation from AC servo systems to motion control system solutions, and its business model is achieving a comprehensive range from single axis to single machine to unit.

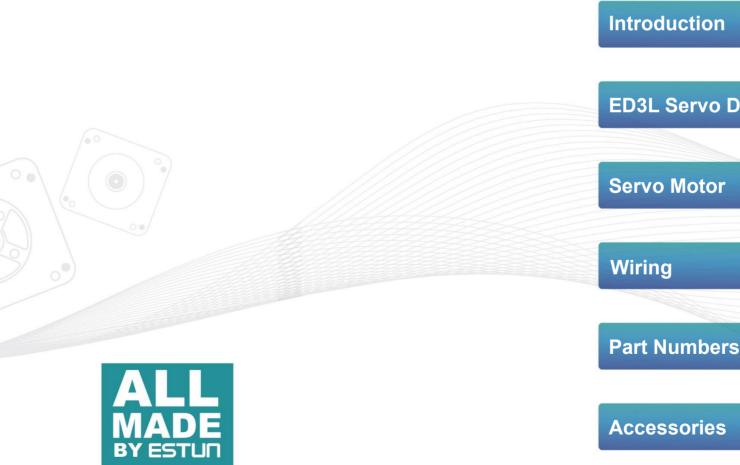
Estun actively explores the "internationalization" development strategy. It has successively acquired Trio (a UK company), became a controlling shareholder of the M.A.I (a Germany company), and invested in companies such as Barrett (a US company), Euclid (an Italian company) and so on, and established a European R&D center in Milan. It has initially completed the international layout in terms of brand and technology, and laid a solid foundation for the implementation of its development strategies in motion control solutions, intelligent cooperative robots, rehabilitation robots and Industry 4.0. At present, Estun Group has 7 oversea branches with businesses in over 60 countries and regions.

In the future, Estun will keep pace with the industrial development trend and take a development path with Estun features. Estun is aimed at supplying the most advanced Chinese motion control system and forming the best Chinese brand. Estun spares no pains to be an international enterprise accepted and respected by market.

A better world worthies our best effort!









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 $172mm \times 40mm \times 180mm$ Dimensions (H×W×D)

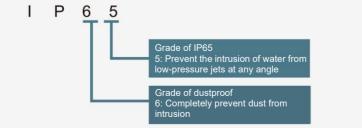
Motor (IP65

supported)

172mm× 55mm× 180mm

172mm ×70mm×180mm





Advantages

Zero Stacking

Supports installation with a spacing of 1mm, saving the space of electrical cabinet

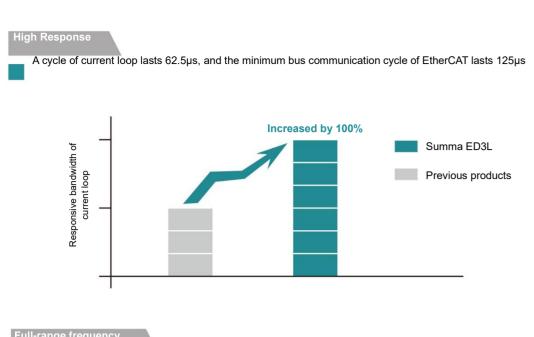
1mm



Comprehensive Protection

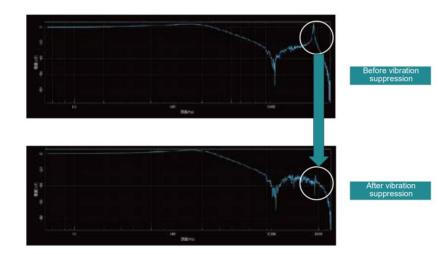
Improve the reliability of product use and fully tap the system performance



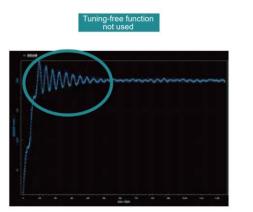


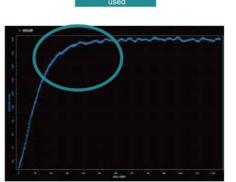
Full-range frequency

Achieve vibration suppression in the full frequency bands from 1Hz to 5000Hz



Support tuning-free, and auto-tuning mode; automatic offline parameter tuning function, to give better usability





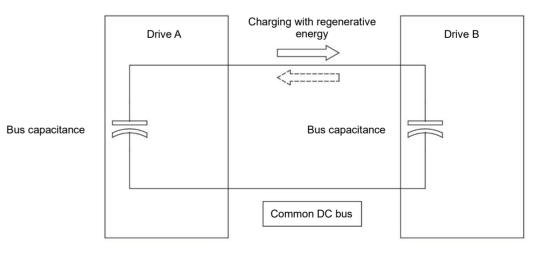
ng-free fun

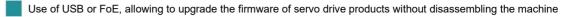


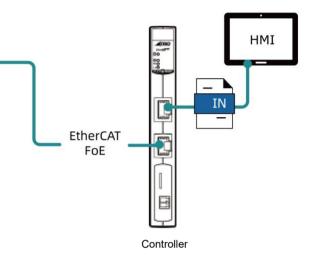




The application of common DC bus can be achieved without special settings, which enhances the utilization efficiency of the bus and saves energy









Specification			
General specifica	tions		
	Item		
Input Power			Three-phase AC200V~2
Control Method			
Feedback			
	Work	Temperature	
	Ambient	Humidity	
	Storage Ambient	Temperature Humidity	
Operating	Protection Structure		
Conditions	Altitude		
	Vibration Resistance	•	
	Impact Resistance		
	Power System		
Installation			
USB communication	Port communications star	ndard	
Display			
Panel Operator			
Regenerative Braking			Products with a rated p
Protection Functions Auxiliary Function			Products with a ra Overcurrent, over Alarm record, JOG ope

ED3L-

	Item		
Torque control	Input signal	Command voltage	
	Contact instruction	Torque set	
Speed control	Input signal	Command voltage	
	Contact instruction	Speed selection	
Position control	Instruction pulse	Туре	Choose one from
1 conton control	PCP instruction	Position set	
	Encoder frequency division pulse output		
I/O Signals	Input signal		
	Output signal		

ED3L-

Item
Input signal
Output signal
Applicable communication standards
Physical layer
Bus connection
Cables
FoE (File Over EtherCAT)

Specification

Single-phase AC 200V~240V, -15% ~+10%, 50Hz/60Hz

-240V, -15%~+10%, 50Hz/60Hz (only applicable to drives with rated power >750W)

SVPWM control

17bit incremental/absolute encoder 20bit incremental encoder 23bit absolute encoder

Single Device: -5°C~55°C Multiple Devices : -5°C~40°C

5%-95%RH (no condensation and freezing)

-20°C ~85°C

5%~95%RH (no condensation and freezing)

IP20

under 1000m

4.9m/s²

19.6m/s²

TN system

Base-mounted

PC (connected to ESView)

Compliant with USB2.0 standard (12 Mbps)

5-digit digital tube

4 keys

power of 50W~400W are provided with no built-in braking resistor, and an external resistor can be installed if necessary

rated power of 750W~2kW are provided with built-in braking resistor ervoltage, low voltage, overload, regeneration error, overspeed, etc peration, load inertia detection, mechanical analyzer, auto tuning tool, etc

Specification

DC±10V(DC±0V~±10V: variable setting range)

4 torque contacts

DC±10V(DC±0V~±10V: variable setting range)

1st speed ~ 7th speed

sign + pulse train, CCW+CW pulse train, 2-phase pulse (90° phase difference) (A phase + B phase) 32 position contacts

Phase A. Phase B. Phase C: Line drive output

Frequency division pulse number: arbitrary frequency division allowed

Operating voltage: 24 VDC ± 20% Input Channel Number: 10 (2 of which can be used for Touch Probe)

Operating voltage: 5 VDC~30 VDC Output Channel Number: 4 (one of which is for servo alarm only)

Specification

Range of operating voltage: 24 VDC ± 20% Number of input channels: 5 (2 of which can be used for Touch Probe) Range of operating voltage: 5 VDC~30 VDC Number of output channels: 3 (one of which is for servo alarm only) IEC 61158 Type12, IEC 61800-7 CiA402 Drive Profile 100BASE-TX (IEEE802.3) CN3-IN (RJ45): EtherCAT Signal IN CN4-OUT (RJ45): EtherCAT Signal OUT Cat.5 twisted pair (4 pairs of shielded twisted pair) Download new firmware using FoE protocol

D Part number	3	Servo Motor												
EM3A-	02	Α	F	Α	2	4	1							
EM3A Servo Motor	Rated output Power	Power voltage	Encoder	Design Sequence	Shaft End	Option Parts	Connector Types							
	Sign Spec. A5 0.05kW 01 0.1kW 02 0.2kW 04 0.4kW 08 0.75kW 10 1.0kW 15 1.5kW 20 2.0kW	Sign Spec. A 200V	Sign Spec. F 20-bit incremental L 23-bit absolute K 17-bit incremental T 17-bit absolute	Sign Spec. A Design sequence	Sign Spec. 2 Flat With key With thread	Sign Spec. Without oil seal Without brake Without brake Without oil seal With brake With brake With brake	Token Spec.							
EMG-	10	Α	F	D	2	2								
EMG Servo Motor	Rated output power	Power voltage	Encoder	Design Sequence	Shaft End	Option Parts								
	Sign Spec. 10 1.0kW 15 1.5kW 20 2.0kW	Sign Spec. A 200V	Sign Spec. F 20-bit incremental L 23-bit absolute K 17-bit incremental	Sign Spec. B,D Design sequence	Sign Spec. 2 Flat With keys With threads	Sign Spec. 1 Without of seal Without brake 2 With oil seal Without brake 3 Without of seal With brake 4 With oil seal With brake								
EM3G-	09	Α	L	Α	2	4	4							
EM3G Servo Notor	Rated output power	Power voltage	Encoder	Design Sequence	Shaft end	Option Parts	Connector Types Sign Spec.							
	Sign Spec. 09 0.85kW 13 1.3kW	Sign Spec. A 200V	Sign Spec. L 23-bit absolute K 17-bit incremental	Sign Spec.	Sign Spec. 2 Flat With keys With threads	Sign Spec. 1 Without oil seal Without brake 2 With oil seal Without oil seal With brake 3 Without oil seal With brake	4 Aviation plug							
EM3J-	08	Α	L	Α	2	4	1							
EM3J Servo Motor	Rated output power Sign Spec.	Power voltage Sign Spec.	Encoder Sign Spec.	Design Sequence Sign Spec.	Shaft End	Option Parts Sign Spec.	Connector Typed Sign Spec.							
	04 0.4kW 08 0.75kW	A 200V	F 20-bit incremental L 23-bit absolute K 17-bit incremental T 17-bit absolute	A Design sequence	2 Flat With keys With threads	Without oil seal Without brake Without brake Without oil seal Without oil seal With brake With oil seal With brake	1 Standard plug 2 Standard IP65 plug							

Specification

20-bit/23-bit Encoder

Voltage				200VAC				
Servo Motor model:				EM3A- 04ALA			1	
Rated Output [kW]	A5ALA	01ALA	02ALA	04AFA	08ALA	10ALA	15ALB	20ALB
Rated torque [N•m]	0.159	0.318	0.637	1.27	2.39	3.18	4.78	6.37
Instantaneous Peak Torque [N•m]	0.557	1.11	2.23	4.45	8.37	9.54	14.3	19.1
Rated Current [Arms]	0.9	1.1	1.5	2.9	5.1	6.9	9.5	12.6
Instantaneous Max Current [Arms]	3.3	4.0	5.8	11.5	19.5	21	31.6	42
Rated Speed [rpm]		30	00					
Max. Speed [rpm]		50	00					
Rotor Moment of interia	0.023	0.0428	0.147	0.244	0.909	1.14	2.33	2.95
[×10 ⁻⁴ kg•m ²]	(0.0268)	(0.0465)	(0.179)	(0.276)	(1.07)	(1.30)	(3.10)	(3.72)
	0.37	0.5	0.9	1.3	2.6	3.1	5.1	6.1
Weight [kg]	(0.59)	(0.7)	(1.3)	(1.7)	(3.2)	(3.8)	(6.4)	(7.5)
Brake Rated Voltage				DC 24\	/±10%			
Brake Rated Power [W]		4.0	7.	.4		9.6	1	7.6
Brake Rated Torque [N•m]		0.32	1.	.5		3.2		8
Encoder	•23-bit absolute encoder 8388608P/R			t incremental enco bit absolute enco			•23-bit abso 8388608P/I	
Insulation Class					F			
Ambient Temperature				0~40°C	(no freezing)			
Ambient Humidity				20%~85%RH	(non-condens	sing)		
Vibratian	•Vibr	ation: less tha	an 49m/s2 (50	G) when rotatir	ng; less than 2	24.5m/s2 (2.5	G) when beir	ig stopped
Vibration				•Impact: less	than 98m/s2 (10G)		
				Self-co	ooled, IP65			
Protection		xcept for sha uipped with I	ft opening, wh P65 plug)	en not equipp	ed with oil sea	al; Except for	connector, w	hen not

Note: The data inside parenthesis represents the values with brake.

Voltage				200VAC								
0		EMG-		EM	13G-	EM	3J-					
Servo Motor model:	10ALB	15ALB	20ALB 20AFD	09ALA	13ALA	04ALA	08ALA					
Rated Output [kW]	1.0	1.5	2.0	0.85	1.3	0.4	0.75					
Rated Torque [N•m]	4.78	7.16	9.55	5.41	8.28	1.27	2.39					
Instantaneous Peak Torque [N•m]	14.3	21.5	28.7	16.2	24.0	4.46	8.37					
Rated Current [Arms]	5.8	8.2	11.3	6.8	9.7	2.8	5.1					
Instantaneous Max current [Arms]	17.4	24.6	33.9	22.6	29.7	11.2	19.5					
Rated Speed [rpm]		2000		15	00	30	00					
Max. Speed [rpm]		3000		30	00	60	00					
Rotor Moment of interia	13.2	18.4	23.5	11.9	17.3	0.64	1.64					
[×10 ⁻⁴ kg•m ²]	(14.3)	(19.5)	(24.6)	(12.5)	(17.9)	(0.68)	(1.69)					
Weight [kg]	7.0	8.9	10.8	5.6	7.0	1.3	2.3					
troigit [tig]	(8.5)	(10.4)	(12.3)	(7.3)	(8.7)	(1.4)	(2.9)					
Brake Rated Voltage			DC	24V±10%								
Brake Rated Power [W]		19.5		2	23	7.4	9.6					
Brake Holding Torque [N•m]		12		2	20	1.5	3.2					
Encoder		ental encoder 104		•23-bit absolute enc	oder 8388608P/R	•20-bit incremental encoder 1048576P/I						
	•23-bit absol	ute encoder 8388	608P/R			 23-bit absolute er 	ncoder 8388608P/R					
Insulation Class				F								
Ambient Temperature			0~4	0°C (No freezir	ng)							
Ambient Humidity			20%~859	%RH (No cond	ensing)							
Resistance to shock	•Vibration: le	ess than 49m/s	s2 (5G) when ro	otating; less tha	an 24.5m/s2 (2	.5G) when bei	ng stopped					
	•Impact: less than 98m/s2 (10G)											
				elf-cooled, IP65								
Protection	(Except fo	or shaft openir	ng, when not eq	uipped with oil ped with IP65 p		or connector, v	vhen not					
			equip		Jug)							

17-bit Encoder

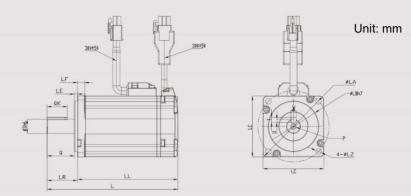
Voltage				200V	/AC						
Servo Motor model:	014//4000	024//4	0441/4	EM3							
Servo Motor model.	01AKA					15AKB	20AKB				
Rated Output [kW]	0.1	0.2	0.4	0.75	1.0	1.5	2				
Rated torque [N•m]	0.318	0.637	1.27	2.39	3.18	4.78	6.37				
Instantaneous Peak Torque [N•m]	0.954	1.91	3.81	7.17	9.54	14.3	19.1				
Rated Current [Arms]	1.1	1.5	2.9	5.1	6.9	9.5	12.6				
Instantaneous Max Current [Arms	3.5 J	4.7	9.2	16.1	21	31.6	42				
Rated Speed [rpm]			3000			3	000				
Max. Speed [rpm]		5	000								
Rotor Moment of interia	0.0428	0.147	0.244	0.909	1.14	2.33	2.95				
[×10 ⁻⁴ kg•m ²]	(0.0465)	(0.179)	(0.276)	(1.07)	(1.30)	(3.10)	(3.72)				
Weight [kg]	0.5	0.9	1.3	2.6	3.1	5.1	6.1				
weight [kg]	(0.7)	(1.3)	(1.7)	(3.2)	(3.8)	(6.4)	(7.5)				
Brake Rated Voltage											
Brake Rated Power [W]	4.0	7.	4	9.0	6	17.6					
Brake Holding Torque [N•m]	0.32	1.	5	3.2	2	8					
Encoder			al encoder 131072 encoder 131072			•17-bit increm 131072P/R	ental encoder				
Insulation Class				F							
Ambient Temperature			0~40)°C (no freezi	ng)						
Ambient Humidity			20%~85%	RH (non-con	densing)						
Resistance to shock	•Vibration:	less than 49m/	s2 (5G) when r	otating; less that	an 24.5m/s2 (2	.5G) when bei	ng stopped				
			•Impact: le	ess than 98m	/s2 (10G)						
			Se	lf-cooled, IP6	5						
Protection	(Except for shaft opening, when not equipped with oil seal; Except for connector, when not equipped with IP65 plug)										
			not equi		o plug)						

Note: The data inside parenthesis represents the values with brake.

Voltage			200VAC		
	EMG-	EM	13G-	EN	13J-
Servo motor model:	10AKB	09AKA	13AKA		
Rated Output [kW]	1.0	0.85	1.3	0.4	0.75
Rated Torque [N•m]	4.78	5.41	8.28	1.27	2.39
Instantaneous Peak Torque [N•m]	14.3	16.2	24.0	3.81	7.17
Rated Current [Arms]	5.8	6.8	9.7	2.8	5.1
Instantaneous Mas Current [Arms]	17.4	22.6	29.7	8.8	16.1
Rated Speed [rpm]	2000	15	30	00	
Max. Speed [rpm]	3000	30	60	00	
Rotor Moment of Interia	13.2	11.9	17.3	0.64	1.64
[×10 ⁻⁴ kg•m ²]	(14.3)	(12.5)	(17.9)	(0.68)	(16.9)
Weight [kg]	7.0	5.6	7.0	1.3	2.3
weight [kg]	(8.5)	(7.3)	(8.7)	(1.4)	(2.9)
Brake Rated Voltage			DC 24V±10%		
Brake Rated Power [W]	19.5	;	23	7.4	9.6
Brake Holding Torque [N•m]	12	1	20	1.5	3.2
				17-bit increme	
Encoder	17-bit i	ncremental encode	er 131072P/R	13107 17-bit absolute en	
Insulation Class			F		
Ambient Temperature		()~40°C (no freezing)		
Ambient Humidity		20%~	85%RH (non-conden	sing)	
Depistence to should	•Vibration: less	than 49m/s2 (5G) wh	en rotating; less than 24	1.5m/s2 (2.5G) when b	eing stopped
Resistance to shock		•Impac	ct: less than 98m/s2 ((10G)	
			Self-cooled, IP65		
Protection			t equipped with oil se	al; Except for conne	ector, when not
	equipped with IP	65 plug)			

Note: The data inside parenthesis represents the values with brake.

Dimensions



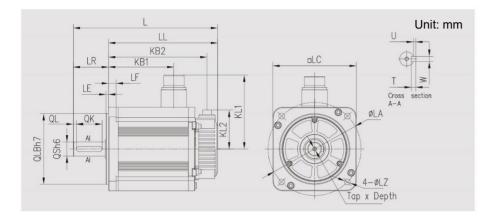
ЕМЗА-	L	ш			Flan	ge Si	ide			s	Ton vDonth		Кеу					
EMDA-			LR	LE	LF	LC	LA	LB	LZ		Tap ×Depth	QК	W	Т	U	Q		
A5ALA	87.5(121)	62.5(96)	25	2.5	5	40	46	30	4.3	8	M3×6	14	3	3	1.8	22.5		
01ALA	103.5(137)	78.5(112)	25	2.5	5	40	46	30	4.3	8	M3×6	14	3	3	1.8	22.5		
02ALA	108(137)	78(107)	30	3	7	60	70	50	5.5	14	M5×12	20	5	5	3	27		
04ALA	129(158)	99(128)	30	3	7	60	70	50	5.5	14	M5×12	20	5	5	3	27		
08ALA	151 (184)	111(144)	40	3	8	80	90	70	6.6	19	M6×12	25	6	6	3.5	37		
10ALA	165 (198)	125(158)	40	3	8	80	90	70	6.6	19	M6×12	25	6	6	3.5	37		
01AFA 01AKA 01ATA	113.5 (147)	88.5 (122)	25	2.5	5	40	46	30	4.3	8	МЗхб	14	3	3	1.8	22.5		
02AFA 02AKA 02ATA	126.5(155.5)	96.5(125.5)	30	3	7	60	70	50	5.5	14	M5×12	20	5	5	3	27		
04AFA 04AKA 04ATA	147.5(176.5)	117.5(146.5)	30	3	7	60	70	50	5.5	14	M5×12	20	5	5	3	27		
08AFA 08AKA 08ATA	167.5 (184)	127.5 (144)	40	3	8	80	90	70	6.6	19	M6×12	25	6	6	3.5	37		
10AFA 10AKA 10ATA	182.5 (214.5)	142.5 (175.5)	40	3	8	80	90	70	6.6	19	M6×12	25	6	6	3.5	37		

EM3J -	L	LL -			Flan	ge Si	ide			s	Tap ×Depth	Кеу						
LINDJ			LR	LE	LF	LC	LA	LB	LZ		Tap >Depth	QK	W	Т	U	Q		
04ALA	129(158)	99(128)	30	3	7	60	70	50	5.5	14	M5×12	20	5	5	3	27		
08ALA	142(175)	102(135)	40	3	8	80	90	70	6.6	19	M6×12	25	6	6	3.5	37		
04AFA 04AKA 04ATA	147.5(176.5)	117.5(146.5)	30	3	7	60	70	50	5.5	14	M5×12	20	5	5	3	27		
08AFA 08AKA 08ATA	158.5(175)	118.5(135)	40	3	8	80	90	70	6.6	19	M6×12	25	6	6	3.5	37		

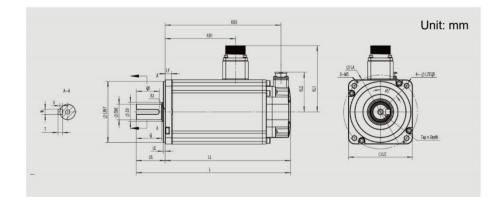
Note: Numbers inside parentheses represents the values with brake.

14





EMG-		LL							S	Тар										
LMO			NDI	KDZ KLI	NLZ	LR	LE	LF	LC	LA	LB	LZ		×Depth	QK	Q	W	Т	U	
100B/D	203(245.5)	148(190.5)	80(103.2)	131.5(174)																
15□□B/D	170(212.5)	170(212.5)	102(125.2)	153.5(196)	117	60.5	55	4	12	130	145	110	9	22	$M6 \times 20$	40	5	8	7	4
200B/D	192(234.5)	192(234.5)	124(147.2)	175.5(218)																



EM3A-		KB1	KB2	KL1	KL2			Flan	ige S	ide			s	Тар					
LMOA		NDI	NDZ	I.LI	NLZ	LR	LE	LF	LC	LA	LB	LZ		×Depth	QK	Q	W	Т	U
	165 (195) 185 (215)			102	60	45	3	10	100	115	95	7	24	M8x16	36	40	8	7	4

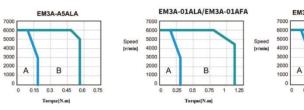
EM3G-		п	KB1	KB2	KI 1	KL2			Flan	ige S	ide			s	Тар					
LING	-		NDI	NDZ	NL1	NLZ	LR	LE	LF	LC	LA	LB	LZ		×Depth	QK	Q	W	т	U
09A□A 13A□A	185 (215) 200 (260)		94.5 109.5	116 (146) 131 (161)	112	58.5	54	6	12	130	145	110	9	22	M6x20	32	40	8	7	4

Note: The data inside parenthesis indicates the value of motor with brake.

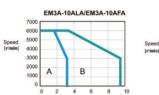
Features

Speed [r/min]

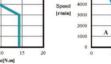
20-bit/23-bit Encoder



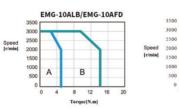
EM3A-15ALB

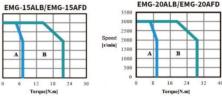


Torquel N.ml



400





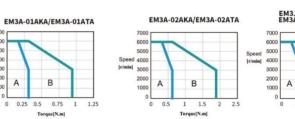
17-bit Encoder

В

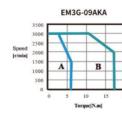
Speed [r/min]

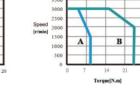
3000

1000

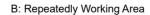


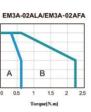
EM3G-13AKA





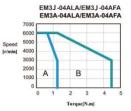
A: Continuous Working Area

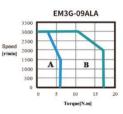


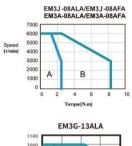


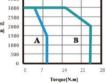






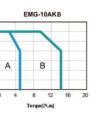






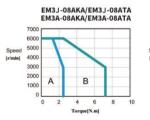


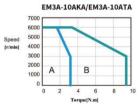




2500 Speed [r/min] 2000 2000 1500 1000

500

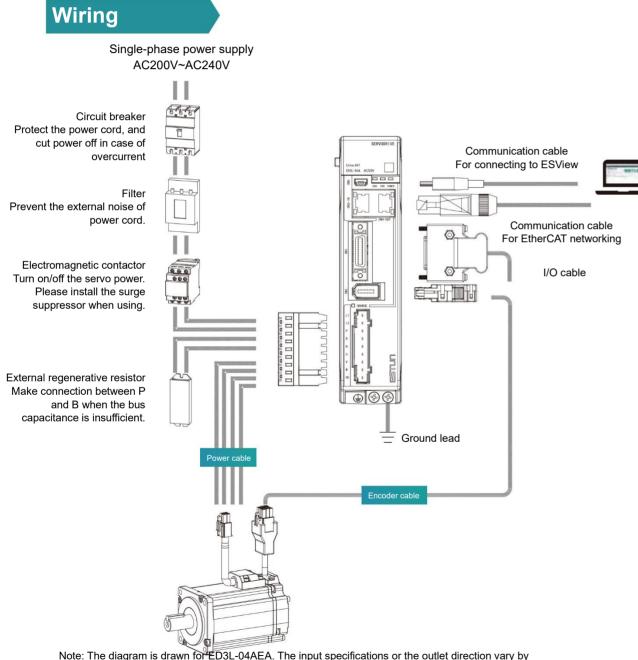








Drive model	Voltage	Power (kW)	Motor model	Power cable	Encoder cable
ED3L-A5A		0.1	EM3A-A5A		
ED3L-01A	Single-phase	0.1	EM3A-01A		
ED3L-02A	200VAC	0.2	EM3A-02A	EC3P-N9118-□□ (without brake) EC3P-B9118-□□ (with brake) EC3P-N9718-□□ (without	EC3S-I1724-□□ (incremental, IP65) EC3S-A1724-□□ (absolute,
ED3L-04A		0.4	EM3A-04A EM3J-04A	brake, IP65) EC3P-B9718-⊡ (with brake, IP65)	IP65) EC3S-I1124-□□ (incremental) EC3S-A1124-□□ (absolute)
ED3L-08A		0.8	EM3A-08A EM3J-08A A EM3J-08A A A		
	Single-phase or		EM3A-10A		
ED3L-10A	Three-phase 200VAC	1.0	EMG-10ABB EMG-10AFD		EC3S-A1324-□□ (absolute) EC3S-I1324-□□ (incremental)
			EM3G-09A		EC3S-A1924-□□ (absolute) EC3S-I1924-□□ (incremental)
		1.5	EMG-15ALB	EC3P-N9314- (without	EC3S-A1324-□□ (absolute) EC3S-I1324-□□ (incremental)
ED3L-15A		1.J	EM3G-13A A	brake) EC3P-B9314-⊡□(with brake)	
	Thursday		EM3A-20A		EC3S-A1924-□□ (absolute) EC3S-I1924-□□ (incremental)
ED3L-20A	Three-phase 200VAC	2.0	EMG-20ALB		EC3S-A1324-□□ (absolute) EC3S-I1324-□□ (incremental)



Note: The diagram is drawn for ED3L-04AEA. The input specifications or the outlet direction vary by model, but the basic system components would be similar.

06 Accessories

Cables

EC3S-A1124- 🗌

Model	Encoder		IP65
EM3A-OOALAOO1 EM3A-OOATAOO1	Absolute		No
(50w-1kw)	Motor-side		Drive-side
	View from insertion	n side	View from welding side
	1 2 3 4 5 6 7 8 9		246810
	Pin No. Signal		Pin No. Signal
	1 S+	-	7 S+
	2 S-		8 S-
	3 BAT+	- T-	• 9 BAT+
	4		5
	5	TD	6
	6 PG5V	-	1 PG5V
	7 PG0V	7	2 PG0V
	8 BAT-	+ o	10 BAT-
	9 FG		Shell FG

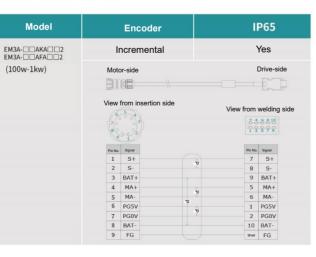
EC3S-I1124- 🗆

Model		Encod	er		IP65
EM3A- AKA 11 EM3A- AFA 11		Increme	ntal		No
(100w-1kw)		tor-side			Drive-side
	View	r from insertion	n side	View from	welding side
		L 2 3 4 5 6 7 8 9			6810 579
	Pin No	 Signal 		Pin No.	Signal
	1	S+	-	7	S+
	2	S-		8	S-
	3	BAT+	↑	9	BAT+
	4	MA+	70	5	MA+
	5	MA-	7	6	MA-
	6	PG5V		1	PG5V
	7	PGOV	U.	2	PGOV
	8	BAT-		10	BAT-
	0				

EC3S-A1724- 🗆

Model	E	ncoder				IP65
EM3A- ALA 2 EM3A- ATA 2	А	bsolute				Yes
(50w-1kw)	Moto	or-side			D	rive-side
	View fro	om insertion	n side	View f	2.4	welding side
	1	Signal S+	0		7	Signal S+
	2	5-	4		8	5-
	3	BAT+			9	BAT+
	4				5	
	5			-	6	
	6	PG5V		-	1	PG5V
	7	PGOV	4		2	PGOV
	8	BAT-	*	•	10	BAT-
	9	FG			Shell	FG
				- +		

EC3S-I1724- 🗆



EC3S-A1324- 🗆

Model	Encode				IP65
EMG-□□ALB2□ 1kw-2kw)	Absolute	e			Yes
	Motor-side			0	Drive-side
			- <u>-</u>]	
	View from insert	ion side	Vie	w from	welding sid
	30 ⁷⁰ 100 20 ⁶⁰ 90 10 ⁵⁰ 80			2 4 0 0 0 0 0 0 1 1	6 8 10 5 7 9
	Pin No, Signal			Pin No.	Signal
	1 S+	(}	- 7	S+
	2 S-			8	S-
	3 BAT+			0 9	BAT+
	5			- 5	
	6	T		6	
	8 PG5V			- 1	PG5V
	7 PG0V			2	PG0V
	4 BAT- 10 FG			10	BAT-

EC3S-A1924-

Model	E	ncoder			I	P65
EM3 A 2 4 (850w-2kw)	Δ	bsolute				Yes
(00011 2.0.1)	Motor-s		*{	-		Drive-side
	View fi	rom insertio	n side	View	from w	elding side
	Pin No.	Signal			Pin No.	Signal
	1	S+			7	S+
	2	S-			8	S-
	3	BAT+			9	BAT+
	4	BAT-	τ.	9	10	BAT-
	8	PG5V			1	PG5V
	7	PGOV		5	2	PG0V



EC3P-N9118-

Model		Brake		IP65	5
M3AA1 50w-1kw)		No		No	
	Motor-s	side		Driv	/e-sid
	(DE		 _	 ~~~	
		~	 		6
		2	 		
		24	 		
		2 4 Sepur	 	Pin No.	Signal
				Pin No.	
	Pin No.	Signal	 	Pin No.	Signal
	Pin No. 1	Signal U		Pin No.	Signal U

EC3S-I1324- 🗆

Model	E	ncoder			IP65	
EMG-10AKB2 EMG-	Incr	emental			Yes	
(1kw-2kw)		m insertion :	side	[ve-side	
	20 5	90 80 80			8 8 10 7 9	
	Pin No.	Signal		Pin No.	Signal	
	1	S+	-	7	S+	
	2	S-		8	S-	
	3	BAT+	*	9	BAT+	
	5	MA+	±	5	MA+	
	6	MA-	P	6	MA-	
	8	PG5V	10	1	PG5V	
	7	PGOV	p	2	PG0V	
	4	BAT-		10	BAT-	

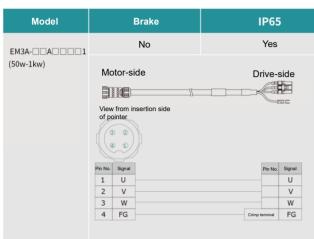
EC3S- I1924 - 🗆 🗆

Model	E	ncoder		1	P65
EM3A2_4 (850w-2kw)	Incre	emental		١	/es
	Motor-s	ide		Drive-	side
		 			þ
	View from	n insertion s	ide		
				View from w	elding side
	Pin No	Signal		Pin No	Signal
	1	S+		7	S+
	2	S-	7	8	S-
	3	BAT+		9	BAT+
	4	MA+	7	10	BAT-
	8	MA-	0	1	PG5V
	7	PG5V		2	PGOV
	10	PG0V	٩	Shell	PG

EC3P-B9118-

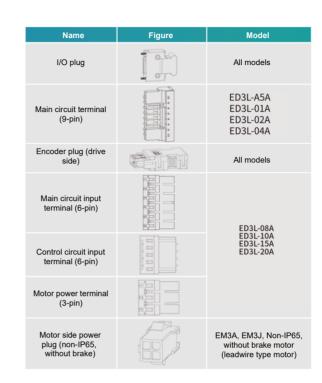
Model		Brake	IP65	5
EM3AA1 (50w-1kw)		Yes	No	
	Motor-s	ide	Driv	ve-side
		2 3 5 6		BT. BZ
	Pin No.	2 3 5 6	Pin No.	BI p BZ p Signal
			Pin No.	
	Pin No.	Signal	Pin No.	Signal
	Pin No.	Signal U	Pin No.	Signal U
	Pin No. 1 2	Signal U V	Pin No.	Signal U V
	Pin No. 1 2 3	Signal U V W		Signal U V W

EC3P-N9718- 🗆



EC3P-B9718- 🗆

Model	Brake	IP65
EM3A-00A0001	Yes	Yes
(50w-1kw)	Motor-side	Drive-side
	5 B1 6 B2	B1 B2



Optional Accessories

Other Auxiliaries

Servo Drive	Main Circuit Voltage	Built-in Regenerative Resistor Specifications	Min.Allowable Resistance	Min.Rated Current for Circuit Breaker
ED3L-A5A	200 ~ 240VAC	-	45Ω	4A
ED3L-01A	200 ~ 240VAC	-	45Ω	4A
ED3L-02A	200 ~ 240VAC	-	45Ω	4A
ED3L-04A	$200 \sim 240 \text{VAC}$	-	45Ω	4A
ED3L-08A	$200 \sim 240 \text{VAC}$	50Ω / 60W	25Ω	6A
ED3L-10A	200 ~ 240VAC	50Ω / 60W	25Ω	6A
ED3L-15A	200~240VAC	40Ω / 80W	25Ω	10A or 16A for single phase
ED3L-20A	200~240VAC	40Ω / 80W	25Ω	16A

EC3P-N9314-

Model	Brake	IP65
EMG-	No	Yes
EMG-002 (1kw-2kw)	Motor-side	Drive-side
EM3A4 (850w-2kw)		
	View from insertion side of pointer	
	Pin No. Signal	Pin No. Signal
	B U	U
	I V F W	V
	C FG	Crimp terminal FG
	D FG Terminated line: Wire BVR	

EC3P-B9314- 🗆

Model	Bra	ike	П	P65	
EMG-DDADDD3	Ye	Yes		Yes	
EMG	Motor-side View from insertion side of pointer		Drive-side		
	Pin No. Signal B U		Pin No	. Signal	
	I V			V	
	F W			W	
	C FG		Crimp terminal	FG	
	D FG	Terminated line: Wire BVR 1.5n	nm2		
	G B1	-		B1	
	H B2			B2	

Name	Figure	Model
Motor-side power plug (non-IP65, with brake)		EM3A, EM3J, non-IP65, motor with brake (leadwire type motor)
Motor-side encoder plug (non-IP65)		EM3A, non-IP65 motor (leadwire type motor)
Motor-side power plug (IP65)		EMG, EM3G, EM3A IP65 motor (0.8kW and above)
Motor-side encoder plug (IP65)		EMG, IP65 motor
Motor-side power plug (IP65, without brake)		EM3A, IP65, brake-free motor (leadwire type motor)
Motor-side power plug (IP65, with brake)		EM3A, IP65, motor with brake (leadwre type motor)
Motor-side encoder plug (IP65)		EM3A, IP65 motor (leadwire type motor)
Motor-side encoder plug (IP65)		EM3A, EM3G IP65motor (0.8kW and above)